

Control 5.0: From Newton to Merton in Popper's Cyber-Social-Physical Spaces

Fei-Yue Wang, *Fellow, IEEE*

Abstract—The future of control in cyberspace of parallel worlds is discussed. It argues for the coming age of Control 5.0, the control technology for the new IT capable of dealing with artificial worlds with VR, AR, AI and robotics. The discipline of automation needs a new interpretation of its core knowledge and skill set of modeling, analysis, and control for cyber-social-physical systems, and a paradigm shift from Newtonian Systems with Newton's Laws or Big Laws with Small Data to Mertonian Systems with Merton's Laws or Small Laws with Big Data.

Index Terms—Control 5.0, parallel control, knowledge automation, CPS, CSP, CPSS, Merton, Wiener, Popper.

I. DOUBLE CONTROL: CRISIS OR OPPORTUNITY

TWO recent events have triggered me to write this editorial. First, I was shocked by the stats of our 2016 graduates at Institute of Automation, Chinese Academy of Sciences (CASIA). According to the official listing of disciplines in China by Ministry of Education, under Level-1 discipline *Automation*, we have several Level-2 disciplines, such as “Double Control”, i.e., *Control Theory and Control Engineering*, traditionally the strongest, *pattern recognition and intelligent systems*, *computer applications*, and *social computing*, the newest. This year, among 53 MS graduates, only one has majored in *Control Engineering*, and among 88 PhD graduates, none in “Double Control”. This is a huge contrast to the situation over a decade ago when I started to take graduates at CASIA, around that time more than 60 % of our graduates were in “Double Control” major. Then, I was surprised by a loud conversation at a super market between two young cashiers. One said to the other that he has determined to get his graduate degree at a new private university I never heard of before, and guess what major is he going to take? *Artificial Intelligence*! His goal is to learn how to build robots to do his job automatically. I have hoped that he would choose automatic control or automation as his field, which offers precisely the knowledge and skill to fulfill his desire.

It is quite unique in the world that all most all major universities in China have a college explicitly named for and dedicated to the field of automation, some even has multiple colleges with automation in its names, a powerful indication of the popularity of automation once in China. Fortunately, after broadcasting my worry about the state of control education via *Wechat*, most of my colleagues in those automation colleges tell me the good news: their enrollments are still very strong, although trends are about the same, relatively less and less students are interested in traditional “Double Control”.

It is my strong belief that the core knowledge and skill set for modeling, analysis, and control in automation are still critical and in broad and deep demand in today's industrial, economic, and social activities. *Automation*, especially “Double Control”, should be thriving and in rapid growth

under current course of technology and development. *AI* and *robotics*, and other intelligent techniques, are not competitors or distractors to automation, they should and must be its good friends and big promoters. Then why the decline in number of graduates in “Double Control”? I believe we need more effort in renewing our message to the new generation in their terms, their thinking, their interests and their culture. We must re-interpret the meaning of modeling, to include models in learning and natural language processing, for example, not just differential and difference equations; the range of analysis, to cover the network topology and cloud connectivity, not just stability and convergence; and the action of control, to consider market/organizational management and socio-economic decision-making, not just feedback control and physical regulation. In short, intelligent technology is the gold opportunity of “Double Control”, not its dark crisis.

As an attempt along this line of thinking for future control and motivated by the recent success of “Industrie 4.0” movement initiated by Germany alliance^[1], I would like to share my thought on “Control 5.0”^[2–3] and my belief that object and scope of control should be extended from Newtonian systems with Newton's Laws to Mertonian systems with Merton's Laws^[4–5], and automation should be considered and carried out in cyber-social-physical (CSP) spaces or cyber-physical-social spaces (CPSS), instead of just in traditional physical spaces or cyber-physical spaces (CPS)^[6–7].

II. CONTROL 5.0: OLD IT, PAST IT, NEW IT

The recent victory of computer Go player AlphaGo is not only a milestone in the quest of AI but also an indication that IT now has entered a new era: from old IT the industrial technology, via past IT the information technology, to new IT the intelligent technology^[8–9], i.e.,

$$\text{IT} = \text{Old IT} + \text{Past IT} + \text{New IT}.$$

Correspondingly, we need a new thinking about future control under the new interpretation of IT. As pointed out in [2–3], we believe that control should enter a new stage of development, namely, Control 5.0.

Control 1.0 was centered around mechanical devices, from float regulators for ancient water clocks and modern toilets, and pressure regulators and centrifugal governors for various systems driven by steam engines and other forms of mechanical power. After J.C. Maxwell's stability analysis of Watt's flyball governor (1868) and E. J. Routh's general stability criterion (1877), based on differential equations or their characteristic equations, the theory of control systems was firmly established. Control 2.0 was mainly about electrical circuit systems, transfer functions and frequency-domain analysis. With Control 2.0, steam engines were replaced by electrical motors, human society was moving from transportation networks to power grids.

With emergence of microprocessors and digital computers 60 years ago, control entered Control 3.0 with state representation and Z-transformation, Kalman Filters, PLC/DCS, real-time control, and modern control theory flourished and became mathematically intensive. The birth of Internet brought in

Citation: Fei-Yue Wang. Control 5.0: From Newton to Merton in Popper's Cyber-Social-Physical Spaces. *IEEE/CAA Journal of Automatica Sinica*, 2016, 3(3): 233–234

Fei-Yue Wang is with the State Key Laboratory of Management and Control for Complex Systems, Institute of Automation, Chinese Academy of Sciences (SKL-MCCS, CASIA), Beijing 100190, China, and also with Research Center of Computational Experiments and Parallel Systems, The National University of Defense Technology, Changsha 410073, China (e-mail: feiyue.wang@ia.ac.cn).

Control 4.0 about 20 years ago, however, with the accelerated grow of new IT today, control development is in a fast transition to the new stage of Control 5.0.

Internet of Things (IoT), big data, cloud computing, AI, robotics, augmented reality, virtual reality, and software-defined systems/everything (SDX) have provided the hardware/software infrastructure and content for Control 5.0. The principle of Control 5.0 is the virtual-real duality (VRD), i.e., intrinsically separating model representation from physical objects and making them independent. In Control 1.0 to 4.0, our effort is making models approximating reality of controlled plants as accurate as possible, since we are dealing with Newtonian systems with Newton's Laws, or Big Laws with Small Data, where causality normally prevails. But in Control 5.0, often our objective is "transforming" actual realities to virtual realities, since we are involving with Mertonian Systems with Merton's Laws, or Small Laws with Big Data, where only association revealed by data or experiences is available, and causality is a luxury that is no longer attainable with limited resources for uncertainty, diversity, and complexity.

To implement VRD for Control 5.0, ACP-based Parallel Control has been proposed as a data-driven approach for deep modeling, analytics, and decision-making, in which Artificial Societies or SDX are used for modeling and representation, Computational Experiments are utilized for analysis and evaluation, and Parallel Execution based virtual-real interactions are employed for control and management^[10–13]. SDX provides a platform for self operating or play which generates big data necessary for knowledge extraction and reinforcement learning. Parallel control offers us an effective mechanism for combing Newton's Laws with Merton's Laws, and integrating descriptive control, predictive control, and prescriptive control, thus covering the entire range of newly defined IT functions, from old, past, to new.

III. THE FUTURE OF CONTROL IN WIENER'S CYBERSPACE OF POPPER'S PARALLEL WORLDS

Over the past decade, ACP-based parallel systems approach have been applied to many fields, from algorithm development for parallel learning, parallel games, parallel dynamic programming, prescriptive simulation, to real-world applications of parallel control, intelligence, management, and transportation^[14–19]. Currently, research and development in this direction are team-oriented and require large resources. In a sense, we are constructing software defined processes, plants, enterprises, and organizations with a large number of algorithms, and those SDX then become data generators and factories for powering data-driven analytics and decision-making of Control 5.0. Knowledge automation, as industrial automation for modern industries, will be essential and critical for the success of parallel control and Control 5.0.

According to Karl Popper's philosophy, the reality is consisting of three worlds in parallel, i.e., physical, mental and artificial worlds. Control 1.0 and 2.0 are mainly dealing with powers and transportation for the physical world, while Control 3.0 and 4.0 are focusing on information and networks in the mental world, now Control 5.0 is bringing in the new artificial world, which has been hidden in the first two worlds before, where resources are data and intelligence, and tools are VR, AR, AI, Robots, and other intelligent machines. Therefore, we must consider and design Control 5.0 systems in cyber-social-physical spaces or cyber-physical-social spaces that cover all three worlds, the current cyber-physical spaces will not be sufficient for Control 5.0 operations.

Clearly, "Double Control" in CSP or CPSS will open a new and endless frontier for automation. Actually, this is still within the vision that Norbert Wiener had outlined in his Cybernetics 70 years ago, but today, IoT, big data, big

computing, big decision, and new IT has made the future of control in cyberspaces of parallel worlds more close to reality.

REFERENCES

- [1] Fei-Yue Wang, Complexity Research and Intelligent Industries: Parallel Era and Industries 5.0, Keynote at Control Engineering Summit, 2014.
- [2] Fei-Yue Wang, Control 5.0: Intelligent Control in Parallel Era, Inaugural Address at CAA Technical Committee on Data-Driven Control, Learning, and Optimization, Beijing, China, June 2015. (in Chinese)
- [3] Fei-Yue Wang, CC 5.0: Intelligent Command and Control Systems in the Parallel Age. *Journal of Command and Control*, 2015, 1(1): 107–120.
- [4] Fei-Yue Wang, Newton vs Merton: From Physical Robots to Web Surrogates. In: Proceedings of the IEEE ICRA, Shanghai, China, 2011.
- [5] Fei-Yue Wang, Software-defined Systems and Knowledge Automation: a Parallel Paradigm Shift from Newton to Merton. *Acta Automatica Sinica*, 2015, 41(1): 1–8 (in Chinese)
- [6] Fei-Yue Wang, The Emergence of Intelligent Enterprises: From CPS to CPSS. *IEEE Intelligent Systems*, 2010, 25(4): 85–88.
- [7] Fei-Yue Wang, The Endless ITS Frontier in CSP Spaces. *IEEE Transactions on Intelligent Transportation Systems*, 2015, 16(4): 1610–1618.
- [8] Fei-Yue Wang, Complexity and Intelligence: From Church-Turning Thesis to AlphaGo Thesis and Beyonds. *Journal of Command and Control*, 2016, 2(1): 1–4 (in Chinese)
- [9] Fei-Yue Wang, Milestone to Future: From AlphaGo to Parallel Intelligence. *Science & Technology Review*, 2016, 34(7): 72–74 (in Chinese)
- [10] Fei-Yue Wang, Parallel System Methods for Management and Control of Complex Systems. *Control and Decision*, 2004, 19(5): 485–489.
- [11] Fei-Yue Wang, Artificial Societies, Computational Experiments, and Parallel Systems: An Investigation on Computational Theory of Complex Social-economic Systems. *Complex Systems and Complexity Science*, 2004, 1(4): 25–35.
- [12] Fei-Yue Wang, From Parallel Universes to Parallel Management Systems. *Finance/Economics/Management Experts*, 2007, 10: 48–51.
- [13] Fei-Yue Wang, Toward a Paradigm Shift in Social Computing: the ACP Approach. *IEEE Intelligent Systems*, 2007, 22(5): 65–67.
- [14] Fei-Yue Wang, Lefel Li, Xing Huang, Yumin Zou, An Investigation on Fundamental Theory of Long Period Continuous Production Emphasizing Effectiveness, Safety and Energy Saving. *Computers and Applied Chemistry*, 2007, 24(12): 1711–1713.
- [15] Fei-Yue Wang, Parallel Control and Management for Intelligent Transportation Systems: Concepts, Architectures, and Applications. *IEEE Transactions on ITS*, 2010, 11(3): 630–638.
- [16] Fei-Yue Wang, Study on Cyber-enabled Social Movement Organizations Based on Social Computing and Parallel Systems. *University of Shanghai for Science and Technology*, 2011, 33(1): 8–17 (in Chinese)
- [17] Fei-Yue Wang, Cyberspace-oriented War Organizations and Operations: An Investigation on Parallel Military Systems of Systems. *Military Operations Research and Systems Engineering*, 2012, 26(3): 5–10.
- [18] Fei-Yue Wang, X 5.0: Parallel Intelligent Systems of Systems in Parallel Era. *Communications of the CCF*, 2015, 11(5): 10–14 (in Chinese)
- [19] Fei-Yue Wang, Intelligence5.0: Parallel Intelligence in Parallel Age. *Journal of the China Society for Scientific and Technical Information*, 2015, 34(6): 563–574 (in Chinese)



Fei-Yue Wang (S'87-M'89-SM'94-F'03) received his Ph.D. in Computer and Systems Engineering from Rensselaer Polytechnic Institute, Troy, New York in 1990. He joined the University of Arizona in 1990 and became a Professor and Director of the Robotics and Automation Lab (RAL) and Program in Advanced Research for Complex Systems (PARCS). In 1999, he founded the Intelligent Control and Systems Engineering Center at the Institute of Automation, Chinese Academy of Sciences (CAS), Beijing, China, under the support of the Outstanding Oversea Chinese Talents Program from the State Planning Council and "100 Talent Program" from CAS, and in 2002, was appointed as the Director of the Key Lab of Complex Systems and Intelligence Science, CAS. In 2011, he became the State Specially Appointed Expert and the Director of the State Key Laboratory of Management and Control for Complex Systems. Dr. Wang's current research focuses on methods and applications for parallel systems, social computing, and knowledge automation. He was the Founding Editor-in-Chief of the International Journal of Intelligent Control and Systems (1995-2000), Founding EiC of IEEE ITS Magazine (2006-2007), EiC of IEEE Intelligent Systems (2009-2012), and EiC of IEEE Transactions on ITS (2009-2016). Currently he is EiC of China's Journal of Command and Control. Since 1997, he has served as General or Program Chair of more than 20 IEEE, INFORMS, ACM, ASME conferences. He was the President of IEEE ITS Society (2005-2007), Chinese Association for Science and Technology (CAST, USA) in 2005, the American Zhu Kezhen Education Foundation (2007-2008), and the Vice President of the ACM China Council (2010-2011). Since 2008, he is the Vice President and Secretary General of Chinese Association of Automation. Dr. Wang is elected Fellow of IEEE, INCOSE, IFAC, ASME, and AAAS. In 2007, he received the 2nd Class National Prize in Natural Sciences of China and awarded the Outstanding Scientist by ACM for his work in intelligent control and social computing. He received IEEE ITS Outstanding Application and Research Awards in 2009 and 2011, and IEEE SMC Norbert Wiener Award in 2014.